

PROJECT / PCMMC: Perception-Driven Coordinated Multi-Robot Motion Control

PCMMC

Main Objective:

Aimed at the development of coordination strategies for teams of mobile robots that improve the overall team perception.

Reference: PTDC/EEA-CRO/100692/2008, Funding: FCT, Start Date: 01-01-2010

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Groups: [Networked Systems – Po](#), [Networked Systems – Po](#)

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